



# **SATA Product Manual**

# **Standard 512E models**

ST10000VE0004 ST8000VE0004

100826082, Rev. F April 2018

# **Document Revision History**

Revision	Date	Pages affected and Description of changes	
Rev. A	09/25/2017	Initial release.	
Rev. B	10/06/2017	7 & 9: Updated Max Sust. Data Transfer Rate to 214MB/s	
Rev. C	10/26/2017	<ul> <li>Updated Table 6: Taiwan - Restricted Substances - Unit row header s= HDD &amp; PCBA</li> <li>Updated fastener penetration depth in Section 3.4 &amp; Fig. 4 = 0.140 in.</li> </ul>	
Rev. D	11/03/2017	5, 8 & 17: Updated Workload ratings to 550TB/year	
Rev. E	02/20/2018	5: Updated bullet to - Supports up to 64 HD cameras plus 16 AI streams 5, 8 & 17: Updated MTBF to 2M hours 7 & 9: Updated Max Sust. Data Transfer Rate to 235MB/s	
Rev. F	04/13/2018	20: Added Regulatory Model Number 25: Added missing side hole metric dimension (28.50 mm)	

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When referring to drive capacity, one gigabyte, or GB, equals one billion bytes and one terabyte, or TB, equals one trillion bytes. Your computer's operating system may use a different standard of measurement and report a lower capacity. In addition, some of the listed capacity is used for formatting and other functions, and thus will not be available for data storage. Actual quantities will vary based on various factors, including file size, file format, features and application software. Actual data rates may vary depending on operating environment and other factors. The export or re-export of hardware or software containing encryption may be regulated by the U.S. Department of Commerce, Bureau of Industry and Security (for more information, visit www.bis.doc.gov), and controlled for import and use outside of the U.S. Seagate reserves the right to change, without notice, product offerings or specifications.

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# Seagate® Technology Support Services

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## 1.0 Introduction

This manual describes the functional, mechanical and interface specifications for the following: Seagate® SkyHawk™ AI model drives:.

Standard 512E models		
ST10000VE0004	ST8000VE0004	

These drives provide the following key features:

- · 2M hour MTBF designed for high write duty cycle across SkyHawk Al
- 256 MB data buffer
- 7200 RPM spindle speed
- ATA AV Command support streaming video command support across SkyHawk AI
- Built-in error recovery for non-stop video streaming
- Compliant with RoHS requirements in China and Europe
- Full-track multiple-sector transfer capability without local processor intervention
- High instantaneous (burst) data-transfer rates (up to 600MB per second)
- · Low activity power
- Native Command Queuing with command ordering to increase performance in demanding applications
- · Performance-tuned for seamless video applications and advanced analytics
- PowerChoice<sup>™</sup> for selectable power savings
- Reliability for 24×7 video surveillance applications
- · Rotational Vibration mitigation of system level rotational vibration inside NVR systems
- SeaTools® diagnostic software performs a drive self-test that eliminates unnecessary drive returns
- State-of-the-art cache and on-the-fly error-correction algorithms
- Streaming video optimization consistent command completion times & ERC support across SkyHawk AI
- · Support for S.M.A.R.T. drive monitoring and reporting
- Supports "16+" drive bays
- Supports ATA8 streaming commands
- Supports latching SATA cables and connectors
- Supports up to 64 HD cameras plus 16 Al streams
- Thermal monitoring and reporting for 24×7 operations
- Top Cover Attached motor for excellent vibration tolerance
- Transient power on management 1.8A spin-up current
- Uncompromising reliability supports flexible surveillance design with case temperatures up to 70°C
- Workload ratings of 550TB/year
- · Worldwide Name (WWN) capability uniquely identifies the drive

Note

Seagate recommends validating the configuration with the selected HBA/RAID controller manufacturer to ensure use of full capacity is supported.

#### 1.1 About the Serial ATA interface

The Serial ATA interface provides several advantages over the traditional (parallel) ATA interface. The primary advantages include:

- Easy installation and configuration with true plug-and-play connectivity. It is not necessary to set any jumpers or other configuration options.
- Thinner and more flexible cabling for improved enclosure airflow and ease of installation.
- Scalability to higher performance levels.

In addition, Serial ATA makes the transition from parallel ATA easy by providing legacy software support. Serial ATA was designed to allow users to install a Serial ATA host adapter and Serial ATA disk drive in the current system and expect all of the existing applications to work as normal.

The Serial ATA interface connects each disk drive in a point-to-point configuration with the Serial ATA host adapter. There is no master/slave relationship with Serial ATA devices like there is with parallel ATA. If two drives are attached on one Serial ATA host adapter, the host operating system views the two devices as if they were both "masters" on two separate ports. This essentially means both drives behave as if they are Device 0 (master) devices.

Note

The host adapter may, optionally, emulate a master/slave environment to host software where two devices on separate Serial ATA ports are represented to host software as a Device 0 (master) and Device 1 (slave) accessed at the same set of host bus addresses. A host adapter that emulates a master/slave environment manages two sets of shadow registers. This is not a typical Serial ATA environment.

The Serial ATA host adapter and drive share the function of emulating parallel ATA device behavior to provide backward compatibility with existing host systems and software. The Command and Control Block registers, PIO and DMA data transfers, resets, and interrupts are all emulated.

The Serial ATA host adapter contains a set of registers that shadow the contents of the traditional device registers, referred to as the Shadow Register Block. All Serial ATA devices behave like Device 0 devices. For additional information about how Serial ATA emulates parallel ATA, refer to the "Serial ATA: High Speed Serialized AT Attachment" specification. The specification can be downloaded from <a href="https://www.serialata.org">www.serialata.org</a>.

# 2.0 Drive specifications

Unless otherwise noted, all specifications are measured under ambient conditions, at 25°C, and nominal power. For convenience, the phrases the drive and this drive are used throughout this manual to indicate the following drive models:

Standard 512E models		
ST10000VE0004	ST8000VE0004	

# 2.1 Specification summary tables

The specifications listed in the following tables are for quick reference. For details on specification measurement or definition, see the appropriate section of this manual.

**Table 1 Drive specifications summary** 

Drive specification	ST10000VE0004 ST8000VE0004		
Formatted (512 bytes/sector)*	10TB	8TB	
Guaranteed sectors	(see Section 2.2)		
Heads	14		
Discs	7	7	
Bytes per logical sector	512		
Bytes per physical sector	40	96	
Recording density, KBPI (Kb/in max)	22	30	
Track density, KTPI (ktracks/in avg.)	38	86	
Areal density, (Gb/in <sup>2</sup> avg)	86	67	
Spindle speed (RPM)	72	00	
Internal data transfer rate (Mb/s max)	26	95	
Max sustained transfer rate, OD read (MB/s)	23	35	
I/O data-transfer rate (MB/s max)	60	00	
ATA data-transfer modes supported	PIO modes 0-4 Multiword DMA modes 0-2 Ultra DMA modes 0-6		
Cache buffer	256MB		
Weight: (maximum)	650g (1.43 lb)		
Average latency	4.16ms		
Power-on to ready (sec) (typ/max)	20/30		
Standby to ready (sec) (typ/max)	20/30		
Startup current (typical) 12V (peak)	1.8A		
Voltage tolerance (including noise)	5V ±5% 12V ±10%		
Non-Operating (Ambient °C)	-40° to 70°		
Operating ambient temperature (min °C)	5°		
Operating temperature (drive case max °C)	70° <sup>†</sup>		
Temperature gradient (°C per hour max)	20°C (operating) 30°C (non-operating)		
Relative humidity	5% to 95% (operating) 5% to 95% (non-operating)		
Relative humidity gradient	30% per hour max		
Altitude, operating	−304.8 m to 3,048 m (−1000 ft to 10,000+ ft)		
Altitude, non-operating (below mean sea level, max)	−304.8 m to 12,192 m (−1000 ft to 40,000+ ft)		
Operational Shock (max at 2 ms)	Read 70 Gs / Write 40 Gs		
Non-Operational Shock (max at 2 ms)	250 Gs		

Drive specification	ST10000VE0004	ST8000VE0004		
5–22 Hz: 0.25 Gs, Limited displacement Vibration, operating 22–350 Hz: 0.50 Gs 350–500 Hz: 0.25 Gs				
Operation Rotational vibration	20-1500Hz	z: 12.5 rads/s²		
Vibration, non-operating	2–500 Hz:	2.27 Grms ref		
Drive acoustics, sound power (bels)				
Idle**		typical) (max)		
Performance seek		3.2 (typical) 3.4 (max)		
Non-recoverable read errors		1 sector per 10 <sup>15</sup> bits read		
Mean Time Between Failure (MTBF) 2,000,000 hrs		,000 hrs		
Average annualized workload rating: <550TB/year. The AFR specification for the product assumes the I/O workload does not exceed annualized workload rate limit of 550TB/year. Workloads exceeding the annual degrade the product AFR and impact reliability as experienced by the particular average annualized workload rate limit is in units of TB per calendar year.		the I/O workload does not exceed the average Workloads exceeding the annualized rate may as experienced by the particular application. The		
Warranty	To determine the warranty for a specific drive, use a web browser to access the following web page: <a href="http://www.seagate.com/support/warranty-and-replacements/">http://www.seagate.com/support/warranty-and-replacements/</a> .  From this page, click on the "Is my Drive under Warranty" link. The following are required to be provided: the drive serial number, model number (or part number) and country of purchase. The system will display the warranty information for the drive.			
Load-unload cycles	300	0,000		
Supports Hotplug operation per Serial ATA Revision 3.2 specification		⁄es		

One GB equals one billion bytes when referring to hard drive capacity.
 Accessible capacity may vary depending on operating environment and formatting.

<sup>\*\*</sup> During periods of drive idle, some offline activity may occur according to the S.M.A.R.T. specification, which may increase acoustic and power to operational levels.

<sup>†</sup> Seagate does not recommend operating at sustained case temperatures above 60°C. Operating at higher temperatures will reduce useful life of the product.

# 2.2 Formatted capacity

ST models	Formatted capacity*	Guaranteed sectors	Bytes per logical sector	
ST10000VE0004	10TB	19,532,873,728	4096	
ST8000VE0004	8TB	15,628,053,168	(emulated at 512-byte sectors)	

<sup>\*</sup>One GB equals one billion bytes when referring to hard drive capacity. Accessible capacity may vary depending on operating environment and formatting..

Note LBA Counts for drive capacities greater than 8TB are calculated based upon the SFF-8447 standard publication. <a href="mailto:ftp://ftp.seagate.com/sff/SFF-8447.PDF">ftp://ftp.seagate.com/sff/SFF-8447.PDF</a>

#### 2.2.1 LBA mode

When addressing these drives in LBA mode, all blocks (sectors) are consecutively numbered from 0 to n-1, where n is the number of guaranteed sectors as defined above.

See Section 4.3.1, "Identify Device command" (words 60-61 and 100-103) for additional information about 48-bit addressing support of drives with capacities over 137GB.

# 2.3 Recording and interface technology

Interface	Serial ATA (SATA)
Recording method	Perpendicular
Recording density, KBPI (Kb/in max)	2230
Track density, KTPI (ktracks/in avg)	386
Areal density (Gb/in <sup>2</sup> avg)	867
Spindle speed (RPM) (± 0.2%)	7200
Internal data transfer rate (Mb/s max)	2695
Maximum Sustained transfer rate (MB/s)	235
I/O data-transfer rate (MB/s max)	600 (Ultra DMA mode 5)

# 2.4 Start/stop times

Power-on to Ready (sec) (typ/max)	20/30
Standby to Ready (sec) (typ/max)	20/30
Ready to spindle stop (sec) (max)	23

# 2.5 Power specifications

The drive receives DC power (+5V or +12V) through a native SATA power connector. See Figure 3 on page 24.

### 2.5.1 Power consumption

Power requirements for the drives are listed in Table 2. Typical power measurements are based on an average of drives tested, under nominal conditions, using 5.0V and 12.0V input voltage at 25°C ambient temperature.

Table 2 DC power requirements

		6.0Gb mode	
Voltage	+5V	+12V	Watts
Regulation	± 5%	± 10%	Total
Avg Idle Current *	0.34	0.29	5.15
Advanced Idle Current *			
Idle_A	0.31	0.28	4.94
Idle_B	0.19	0.20	3.41
Idle_C	0.20	0.14	2.74
Standby	0.17	0.02	1.11
Operating current (random read 4K16Q):			
Typical DC	0.34	0.54	8.12
Maximum DC	0.34	0.57	
Maximum DC (peak)	0.96	2.18	
Operating current (random write 4K16Q)			
Typical DC	0.35	0.56	8.49
Maximum DC	0.35	0.59	
Maximum DC (peak)	0.79	2.24	
Operating current (sequential read 64K16Q)			
Typical DC	0.71	0.31	7.21
Maximum DC	0.71	0.31	
Maximum DC (peak)	0.99	1.82	
Operating current (sequential write 64K16Q)			
Typical DC	0.64	0.33	7.16
Maximum DC	0.64	0.34	
Maximum DC (peak)	0.83	1.82	

<sup>\*</sup>During periods of drive idle, some offline activity may occur according to the S.M.A.R.T. specification, which may increase acoustic and power to operational levels

#### 2.5.1.1 Typical current profiles



Figure 1. Typical 5V and 12V startup and operation current profiles

#### 2.5.2 Conducted noise

Input noise ripple is measured at the host system power supply across an equivalent 80-ohm resistive load on the +12 V line or an equivalent 15-ohm resistive load on the +5 V line.

- Using 12V power, the drive is expected to operate with a maximum of 120mV peak-to-peak square-wave injected noise at up to 10MHz.
- Using 5V power, the drive is expected to operate with a maximum of 100mV peak-to-peak square-wave injected noise at up to 10MHz.

Note Equivalent resistance is calculated by dividing the nominal voltage by the typical RMS read/write current.

#### 2.5.3 Voltage tolerance

Voltage tolerance (including noise):

 $5V \pm 5\%$   $12V \pm 10\%$ 

#### 2.5.4 Extended Power Conditions - PowerChoice™

Utilizing the load/unload architecture a programmable power management interface is provided to tailor systems for reduced power consumption and performance requirements.

The table below lists the supported power conditions available in PowerChoice. Power conditions are ordered from highest power consumption (and shortest recovery time) to lowest power consumption (and longest recovery time) as follows: Idle\_a power >= Idle\_b power >= Idle\_c power >= Standby\_z power. The further users go down in the table, the more power savings is actualized. For example, Idle\_b results in greater power savings than the Idle\_a power condition. Standby results in the greatest power savings.

Power Condition Name	Power Condition ID	Description
Idle_a	81 <sub>H</sub>	Reduced electronics
Idle_b	82 <sub>H</sub>	Heads unloaded. Disks spinning at full RPM
Idle_c	83 <sub>H</sub>	Heads unloaded. Disks spinning at reduced RPM
Standby_z	00 <sub>H</sub>	Heads unloaded. Motor stopped (disks not spinning)

Each power condition has a set of current, saved and default settings. Default settings are not modifiable. Default and saved settings persist across power-on resets. The current settings do not persist across power-on resets. At the time of manufacture, the default, saved and current settings are in the Power Conditions log match.

# PowerChoice is invoked using one of two methods

- Automatic power transitions which are triggered by expiration of individual power condition timers. These timer values may be customized and enabled using the Extended Power Conditions (EPC) feature set using the standardized Set Features command interface.
- Immediate host commanded power transitions may be initiated using an EPC Set Features "Go to Power Condition" subcommand to enter any supported power condition. Legacy power commands Standby Immediate and Idle Immediate also provide a method to directly transition the drive into supported power conditions.

# PowerChoice exits power saving states under the following conditions

- Any command which requires the drive to enter the PMO: Active state (media access)
- · Power on reset

## PowerChoice provides the following reporting methods for tracking purposes

**Check Power Mode Command** 

• Reports the current power state of the drive

**Identify Device Command** 

- EPC Feature set supported flag
- EPC Feature enabled flag is set if at least one Idle power condition timer is enabled

Power Condition Log reports the following for each power condition

- Nominal recovery time from the power condition to active
- If the power condition is Supported, Changeable, and Savable
- · Default enabled state, and timer value
- Saved enabled state, and timer value
- Current enabled state, and timer value

#### S.M.A.R.T. Read Data Reports

- · Attribute 192 Emergency Retract Count
- Attribute 193 Load/Unload Cycle Count

#### **PowerChoice Manufacture Default Power Condition Timer Values**

Default power condition timer values have been established to assure product reliability and data integrity. A minimum timer value threshold of two minutes ensures the appropriate amount of background drive maintenance activities occur. Attempting to set a timer values less than the specified minimum timer value threshold will result in an aborted EPC "Set Power Condition Timer" subcommand.

Power Condition Name	Manufacturer Default Timer Values
Idle_a	100ms
Idle_b	2 min
Idle_c	4 min
Standby_z	15 min

Setting power condition timer values less than the manufacturer specified defaults or issuing the EPC "Go to Power Condition" subcommand at a rate exceeding the default timers may limit this products reliability and data integrity.

## **PowerChoice Supported Extended Power Condition Feature Subcommands**

EPC Subcommand	Description
00 <sub>H</sub> Restore Power Condition Settings	
01 <sub>H</sub>	Go to Power Condition
02 <sub>H</sub>	Set Power Condition Timer
03 <sub>H</sub>	Set Power Condition State
04 <sub>H</sub>	Enable EPC Feature Set
05 <sub>H</sub>	Disable EPC Feature Set

# **PowerChoice Supported Extended Power Condition Identifiers**

Power Condition Identifiers	Power Condition Name
00 <sub>H</sub>	Standby_z
01 - 80 <sub>H</sub>	Reserved
81 <sub>H</sub>	Idle_a
82 <sub>H</sub>	Idle_b
83 <sub>H</sub>	Idle_c
84 - FE <sub>H</sub>	Reserved
FF <sub>H</sub>	All EPC Power Conditions

#### 2.6 Environmental limits

Temperature and humidity values experienced by the drive must be such that condensation does not occur on any drive part. Altitude and atmospheric pressure specifications are referenced to a standard day at 58.7°F (14.8°C).

Note

To maintain optimal performance drives should be run at nominal drive temperatures and humidity.

#### 2.6.1 Temperature

#### a. Operating

41°F to 158°F (5°C to 70°C) drive case temperature range with a maximum temperature gradient of 36°F (20°C) per hour.

Note

Seagate does not recommend operating at sustained case temperatures above 60°C Operating at higher temperatures will reduce useful life of the product.

The maximum allowable drive case temperature is 158°F (70°C).

Air flow may be required to achieve consistent nominal case temperature values (see Section 3.4). To confirm that the required cooling is provided for the electronics and HDA, place the drive in its final mechanical configuration, and perform random write/read operations. After the temperatures stabilize, measure the case temperature of the drive. See Figure 2 for HDA temperature checkpoint.

## b. Non-operating

-40° to 158°F (-40° to 70°C) package ambient with a maximum gradient of 36°F (20°C) per hour. This specification assumes that the drive is packaged in the shipping container designed by Seagate for use with drive.

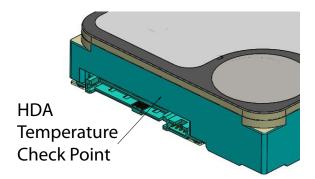


Figure 2. Location of the HDA temperature check point

Note

Image is for reference only, may not represent actual drive

### 2.6.2 Humidity

The values below assume that no condensation on the drive occurs. Maximum wet bulb temperature is 84.2°F (29°C).

## 2.6.2.1 Relative humidity

Operating:	5% to 95% non-condensing relative humidity with a maximum gradient of 20% per hour.
Nonoperating: 5% to 95% non-condensing relative humidity with a maximum gradient of 20% per hour.	

#### 2.6.3 Effective Altitude (sea level)

Operating: -304.8 m to 3048 m (-1000 ft. to 10,000+ ft.)	
Nonoperating: -304.8 m to 12,192 m (-1000 ft. to 40,000+ ft.)	

#### 2.6.4 Shock

All shock specifications assume that the drive is mounted securely with the input shock applied at the drive mounting screws. Shock may be applied in the X, Y or Z axis.

#### 2.6.4.1 Operating shock

These drives comply with the performance levels specified in this document when subjected to a maximum operating shock of 70 Gs (read) and 40 Gs (write) based on half-sine shock pulses of 2ms. Shocks should not be repeated more than two times per second.

#### 2.6.4.2 Nonoperating shock

The nonoperating shock level that the drive can experience without incurring physical damage or degradation in performance when subsequently put into operation is 250 Gs based on a nonrepetitive half-sine shock pulse of 2ms duration.

#### 2.6.5 Vibration

All vibration specifications assume that the drive is mounted securely with the input vibration applied at the drive mounting screws. Vibration may be applied in the X, Y or Z axis.

#### 2.6.5.1 Operating vibration

The maximum vibration levels that the drive may experience while meeting the performance standards specified in this document are specified below.

5–22 Hz	0.25 Gs
22-350 Hz	0.50 Gs
350-500 Hz	0.25 Gs
20 - 1500Hz *(RROV)	12.5 rads/s <sup>2</sup> w/RVFF

<sup>\*</sup> Rotary Random Operating Vibration

#### 2.6.5.2 Nonoperating vibration

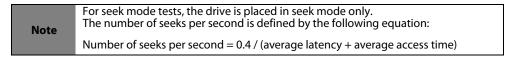
The maximum nonoperating vibration levels that the drive may experience without incurring physical damage or degradation in performance when subsequently put into operation are specified below.

'n		
	2–500 Hz Linear Random	2.27 Grms ref

Freq (Hz)	2	4	100	500
G <sup>2</sup> /Hz	.001	.03	.03	.001

#### 2.7 Acoustics

Drive acoustics are measured as overall A-weighted acoustic sound power levels (no pure tones). All measurements are consistent with ISO document 7779. Sound power measurements are taken under essentially free-field conditions over a reflecting plane. For all tests, the drive is oriented with the cover facing upward.



#### Table 3 Fluid Dynamic Bearing (FDB) motor acoustics

Idle*	Performance seek	
2.8 bels (typ)	3.2 bels (typ)	
3.0 bels (max)	3.4 bels (max)	

<sup>\*</sup>During periods of drive idle, some offline activity may occur according to the S.M.A.R.T. specification, which may increase acoustic and power to operational levels.

## 2.8 Test for Prominent Discrete Tones (PDTs)

Seagate follows the ECMA-74 standards for measurement and identification of PDTs. An exception to this process is the use of the absolute threshold of hearing. Seagate uses this threshold curve (originated in ISO 389-7) to discern tone audibility and to compensate for the inaudible components of sound prior to computation of tone ratios according to Annex D of the ECMA-74 standards.

# 2.9 Electromagnetic immunity

When properly installed in a representative host system, the drive operates without errors or degradation in performance when subjected to the radio frequency (RF) environments defined in the following table:

Table 4 Radio frequency environments

Test Description		Performance level	Reference standard
Electrostatic discharge Contact, HCP, VCP: ± 4 kV; Air: ± 8 kV		В	EN 61000-4-2: 95
Radiated RF immunity  80 to 1000 MHz, 3 V/m, 80% AM with 1 kHz sine 900 MHz, 3 V/m, 50% pulse modulation @ 200 Hz		A	EN 61000-4-3: 96 ENV 50204: 95
Electrical fast transient $\pm$ 1 kV on AC mains, $\pm$ 0.5 kV on external I/O		В	EN 61000-4-4: 95
Surge immunity $\pm$ 1 kV differential, $\pm$ 2 kV common, AC mains		В	EN 61000-4-5: 95
Conducted RF immunity 150 kHz to 80 MHz, 3 Vrms, 80% AM with 1 kHz sine		Α	EN 61000-4-6: 97
Voltage dips, interrupts  0% open, 5 seconds 0% short, 5 seconds 40%, 0.10 seconds 70%, 0.01 seconds		C C C B	EN 61000-4-11: 94

# 2.10 Reliability

#### 2.10.1 Annualized Failure Rate (AFR) and Mean Time Between Failures (MTBF)

The production disk drive shall achieve an annualized failure-rate of 0.44% (MTBF of 2,000,000 hours) over a 5 year service life when used in Storage field conditions as limited by the following:

- 8760 power-on hours per year.
- HDA temperature as reported by the drive <= 30°C
- Ambient wet bulb temp <= 26°C
- · Typical workload
- The AFR (MTBF) is a population statistic not relevant to individual units
- ANSI/ISA S71.04-2013 G2 classification levels and dust contamination to ISO 14644-1 Class 8 standards (as measured at the device)

The MTBF specification for the drive assumes the operating environment is designed to maintain nominal drive temperature and humidity. Occasional excursions in operating conditions between the rated MTBF conditions and the maximum drive operating conditions may occur without significant impact to the rated MTBF. However continual or sustained operation beyond the rated MTBF conditions will degrade the drive MTBF and reduce product reliability..

Nonrecoverable read errors	1 per 10 <sup>15</sup> bits read, max	
Load unload cycles 300,000 cycles		
Average annualized workload rating: <550TB/year. The AFR specification for the product assumes the I/O workload does not exceed the average alized workload rate limit of 550TB/year. Workloads exceeding the annualized rate may deground AFR and impact reliability as experienced by the particular application. The average ized workload rate limit is in units of TB per calendar year.		
To determine the warranty for a specific drive, use a web browser to access the following <a href="http://www.seagate.com/support/warranty-and-replacements/">http://www.seagate.com/support/warranty-and-replacements/</a> .  Warranty  From this page, click on the "Is my Drive under Warranty" link. The following are required vided: the drive serial number, model number (or part number) and country of purchase. will display the warranty information for the drive.		
Preventive maintenance	ve maintenance None required.	

#### 2.10.2 Storage

Maximum storage periods are 180 days within original unopened Seagate shipping package or 60 days unpackaged within the defined non-operating limits (refer to environmental section in this manual). Storage can be extended to 1 year packaged or unpackaged under optimal environmental conditions (25°C, <40% relative humidity non-condensing, and non-corrosive environment). During any storage period the drive non-operational temperature, humidity, wet bulb, atmospheric conditions, shock, vibration, magnetic and electrical field specifications should be followed.

## 2.10.3 Warranty

To determine the warranty for a specific drive, use a web browser to access the following web page: <a href="http://www.seagate.com/support/warranty-and-replacements/">http://www.seagate.com/support/warranty-and-replacements/</a>

From this page, click on "Is my Drive under Warranty". Users will be asked to provide the drive serial number, model number (or part number) and country of purchase. The system will display the warranty information for the drive.

#### 2.10.4 Seagate® Rescue™ Data Recovery Service Program Terms (for +Rescue models)

5-year HDD warranty coverage + concurrent 2 year Rescue Data Recovery service.

#### To enable Rescue Data Recovery warranty coverage register at Seagate.com/register.

If you suffer a data loss event within the first 2 years of your 5 year warranty and you are eligible to participate in and submit a case under the Seagate Rescue Data Recovery program, contact SRS at 800-475-0143 or if you are calling from outside the US, please visit our website for numbers in your local and language: <a href="http://www.seagate.com/services-software/recover/resources/">http://www.seagate.com/services-software/recover/resources/</a>.

An SRS representative will review your case to confirm your eligibility, and to assess whether your data may be recoverable by remote recovery services or whether you will need to send your device to SRS for in-lab servicing.

#### Rescue™ General Terms

These Rescue™ General Terms together with the Rescue™ FAQ's make up the Rescue™ Program Terms. By submitting a case under the Rescue™ program ("Program") you agree to be bound by the Program Terms, including these General Terms and the FAQ

#### Communications.

All communications relating to your request will be available on our web site in your account and sent via e-mail to the address you provide to us unless you request, in writing, to receive such communications via regular mail.

#### Personal Data.

You must provide true, accurate and complete information about yourself as prompted by the request form, including, without limitation, your name, address, e-mail address, and telephone number, as applicable (collectively, "Personal Data"). You must maintain and promptly update your Personal Data. You acknowledge that we may send you important information and notices regarding your requests by e-mail and that we shall have no liability associated with or arising from your failure to maintain accurate Personal Data.

#### Capacity; Legal Rights; Indemnity.

You represent to SRS that you are of the legal age of majority in your state or country of residence, with the full capacity to agree to these Program Terms. You warrant that you are the legal owner or the authorized representative of the legal owner of the device you submit to SRS (the "Device") and data. You warrant that the data on the Device is legal and that you have the unrestricted legal right to (a) give us remote access to the data, (b) have the data recovered and reproduced on a backup medium, (c) receive the recovered data, and (d) agree to these Program Terms. You will defend and indemnify us (including our directors, officers, employees, agents, delegates, and contractors) from any claims or actions relating to the Device or data, or your rights or lack of rights thereto.

#### Confidentiality.

We will protect the confidentiality of your data against unauthorized disclosure using the same degree of care as we use to protect our own confidential information.

#### Disclaimer of Warranties, Representations and Guarantees.

WE PROVIDE THE PROGRAM AND ANY SERVICES PROVIDED OR ATTEMPTED HEREUNDER "AS IS," WITH ALL FAULTS, AT YOUR SOLE RISK. WE DO NOT EXTEND ANY EXPRESS WARRANTIES, REPRESENTATIONS, CONDITIONS OR GUARANTEES REGARDING OUR RESCUE SERVICES OR ANY RESULTS THEREOF. TO THE MAXIMUM EXTENT PERMITTED BY APPLICABLE LAW AND SUBJECT TO ANY STATUTORY WARRANTIES THAT CANNOT BE EXCLUDED, WE EXPRESSLY DISCLAIM ALL IMPLIED WARRANTIES, INCLUDING ANY IMPLIED WARRANTY OR CONDITION OF MERCHANTABILITY, WARRANTY OF FITNESS FOR A PARTICULAR PURPOSE, OR WARRANTY OF ACCURACY OR COMPLETENESS WITH RESPECT TO THIS PROGRAM AND SERVICES. This Program and Disclaimer is unrelated to, and does not affect any warranties relating to your Device that we or the seller may have extended to you.

# Limitation of Liability.

WE WILL NOT BE LIABLE FOR ANY HARM CAUSED, UNLESS YOU PROVE THAT WE CAUSED SUCH HARM INTENTIONALLY. WITHOUT LIMITING THE GENERALITY OF THE FOREGOING, WE WILL NOT BE LIABLE FOR THE CONDITION, EXISTENCE, OR LOSS OF THE DATA YOU SEND US OR THE DATA WE RECOVER (IF ANY), ANY LOSS OF REVENUE OR LOSS OF PROFITS, OR ANY INDIRECT, SPECIAL, INCIDENTAL, OR CONSEQUENTIAL DAMAGES HOWEVER CAUSED. TO THE MAXIMUM EXTENT PERMITTED BY APPLICABLE LAW, THIS LIMITATION SHALL APPLY TO ANY AND ALL DAMAGES, REGARDLESS OF THE LEGAL THEORY ON WHICH THEY ARE ASSERTED (INCLUDING, WITHOUT LIMITATION, CONTRACT, BREACH OF CONTRACT, AND TORT), AND REGARDLESS OF WHETHER WE HAVE BEEN ADVISED OF THE POSSIBILITY OF LOSS OR DAMAGES - UNLESS YOU PROVE THAT SRS CAUSED DAMAGES TO YOU INTENTIONALLY. TO THE MAXIMUM EXTENT PERMITTED BY APPLICABLE LAW, THE AMOUNT OF OUR LIABILITY WILL NOT EXCEED THE TOTAL PRICE YOU ACTUALLY PAY FOR THE DEVICE, THE ESSENTIAL PURPOSE OF WHICH IS TO LIMIT OUR LIABILITY ARISING FROM OR RELATED TO THE PROGRAM AND ANY DATA RECOVERY SERVICES.

THIS ALLOCATION OF RISK IS REFLECTED IN THE PRICE CHARGED FOR THIS PROGRAM OR SERVICES, IF ANY. YOU ACKNOWLEDGE THAT THE PRICE OF THIS PROGRAM WOULD BE MUCH GREATER IF WE UNDERTOOK MORE EXTENSIVE LIABILITY. THIS PARAGRAPH WILL APPLY NOTWITHSTANDING ANY OTHER PROVISIONS IN THESE TERMS, OR THE FAILURE OF ANY REMEDY.

#### Compliance with Laws.

You agree to comply with all such laws and regulations and all other applicable laws, statutes, ordinances and regulations relating to the Program. You acknowledge that violations of these Program Terms could subject you to criminal or civil penalties. The goods licensed or provided, or services provided, through the Program, which may include technology and software, are subject to the customs and export control laws and regulations of the U.S. and may also be subject to the customs and export laws and regulations of the country in which the products are manufactured or received. Further, under U.S. law, such goods may not be sold, leased or otherwise transferred to restricted countries, or used by a restricted end-user or an end-user engaged in activities related to weapons of mass destruction including, without limitation, activities related to designing, developing, producing or using nuclear weapons, materials, or facilities, missiles or supporting missile projects, or chemical or biological weapons. You acknowledge you are not a restricted end-user or involved in any of the restricted activities above, and that you will comply with and abide by these laws and regulations. Seagate reserves the right to refuse service to or the return of any storage devices that have been determined to violate these regulations.

#### Cancellation.

You may cancel the Program at any time by contacting SRS at 1-800-SEAGATE (1-800-475-0143) in the US, or at such other number available at <a href="http://www.seagate.com/services-software/recover/resources/">http://www.seagate.com/services-software/recover/resources/</a>, or you simply may refrain from submitting a request for Rescue services. These Program Terms remain applicable to your and SRS's rights and obligations with respect to any services requested by you under this Program.

#### Assignment.

You may not assign your rights or obligations under these Program Terms without SRS' express written consent.

#### **Dispute Resolution.**

The parties will attempt to resolve any dispute arising out of or related to these Program Terms or any data recovery services requested or attempted hereunder through good faith negotiation. To the extent permitted by applicable law, if the parties are unable to resolve the dispute through good faith negotiation, then the dispute will be submitted to final and binding arbitration with the Judicial Arbitration and Mediation Services. Each party will bear its own costs in arbitration, provided that Seagate reserves the right, in its discretion, to pre-pay certain fees you may incur in connection with the arbitration subject to refund if you do not prevail. **Both parties waive their rights to a jury trial.** All proceedings will take place in Santa Clara County, California, USA. The laws of the State of California will exclusively govern these Program Terms and our provision of any data recovery services, without regard to California's conflicts of laws rules. You consent to the exclusive jurisdiction of the courts located in Santa Clara County, California, USA.

#### Severability.

If any provision of these Program Terms is held invalid, illegal or unenforceable, such provision shall be enforced to the fullest extent permitted by applicable law and the validity, legality and enforceability of the remaining provisions shall not be affected thereby.

#### Legal Effect.

These Program Terms describe certain legal rights. You may have other rights under applicable law. These Program Terms do not change your rights under applicable law if such laws do not permit these Program Terms to do so. Also, the Program and these Program Terms are in addition and unrelated to any rights you may have under a Seagate warranty statement.

## **SRS Companies.**

The following SRS companies may provide the services described in these Program Terms:

- (a) Seagate Technology LLC, with offices at 3101 Jay Street, Suite 110, Santa Clara, California 95054;
- (b) Seagate Technology Canada Inc., with offices at 2421 Bristol Circle, Suite A100, Oakville, Ontario, Canada L6H 5S9; and/or
- (c) Seagate Technology (Netherlands) B.V., with offices at Koolhovenlaan 1, 1119 PA, Schiphol-Rijk, The Netherlands.

## 2.11 Agency and Safety Certifications

Each Hard Drive and Solid State Drive ("drives") has a product label that includes certifications that are applicable to that specific drive. The following information provides an overview of requirements that may be applicable to the drive.

#### 2.11.1 Safety certification

The drives are recognized in accordance with UL/cUL 60950-1 and EN 60950-1.

The following regulatory model number represent all features and configurations within the series: Regulatory Model Numbers: STR00D

#### 2.11.2 European Union (EU) CE Marking Requirements

Drives that display the CE mark comply with the European Union (EU) requirements specified in the Electromagnetic Compatibility Directive (2014/30/EU) put into force on 20 April 2016. Testing is performed to the levels specified by the product standards for Information Technology Equipment (ITE). Emission levels are defined by EN 55032:2012, Class B and the immunity levels are defined by EN 55024:2010.

The drives also meet the requirements of The Low Voltage Directive (LVD) 2014/35/EU.

Seagate drives are tested in representative end-user systems. Although CE-marked Seagate drives comply with all relevant regulatory requirements and standards for the drives, Seagate cannot guarantee that all system-level products into which the drives are installed comply with all regulatory requirements and standards applicable to the system-level products. The drive is designed for operation inside a properly designed system (e.g., enclosure designed for the drive), with properly shielded I/O cable (if necessary) and terminators on all unused I/O ports. Computer manufacturers and system integrators should confirm EMC compliance and provide CE marking for the system-level products.

For compliance with the RoHS "Recast" Directive 2011/65/EU (RoHS 2), See Section 2.12.2 on page 21.

#### 2.11.3 Australian RCM Compliance Mark

If these models have the RCM marking, they comply with the Australia/New Zealand Standard AS/NZ CISPR32 and meet the Electromagnetic Compatibility (EMC) Framework requirements of the Australian Communication and Media Authority (ACMA).

# 2.11.4 Canada ICES-003

If this model has the ICES-003:2016 marking it complies with requirements of ICES tested per ANSI C63.4-2014.

#### 2.11.5 South Korean KC Certification Mark

The South Korean KC Certification Mark means the drives comply with paragraph 1 of Article 11 of the Electromagnetic Compatibility control Regulation and meet the Electromagnetic Compatibility (EMC) Framework requirements of the Radio Research Agency (RRA) Communications Commission, Republic of Korea. These drives have been tested and comply with the Electromagnetic Interference/ Electromagnetic Susceptibility (EMI/EMS) for Class B products. Drives are tested in a representative, end-user system by a Korean-recognized lab.

기 종 별	사 용 자 안 내 문
B 급 기기 (가정용 방송통신기자재)	이 기기는 가정용(B급) 전자파적합기기로서 주로 가정에서 사용하는 것을 목적으로 하며, 모든 지역에서 사용할 수 있습니다.

#### 2.11.6 Morocco Commodity Mark

To satisfy our OEM customers, Seagate has added the Moroccan Commodity Mark to the drives provided to the OEM for the sale of Customer Kits produced by our OEM customers that are intended to be incorporated into the OEM's finished system-level product by an end user. The Customer Kits are considered 'devices' under Morocco's Order of the Minister of Industry, Trade, Investment and Digital Economy No. 2574-14 of 29 Ramadan 1436 (16 July 2015) on electromagnetic compatibility of equipment.

Seagate drives are tested for compliance and complies with the European Union (EU) Electromagnetic Compatibility (EMC) Directive 2014/30/EU and the Low Voltage Directive (LVD) 2014/35/EU. Accordingly, the drives also meets the requirements of Morocco's Order of the Minister of Industry, Trade, Investment and Digital Economy No. 2574-14 of 29 Ramadan 1436 (16 July 2015) on electromagnetic compatibility of equipment.

#### 2.11.7 Taiwanese BSMI

Drives with the Taiwanese certification mark comply with Chinese National Standard, CNS13438.

For compliance with the Taiwan Bureau of Standards, Metrology and Inspection's (BSMI) requirements, See Section 2.12.4 on page 22.

#### 2.11.8 FCC verification

These drives are intended to be contained solely within a personal computer or similar enclosure (not attached as an external device). As such, each drive is considered to be a subassembly even when it is individually marketed to the customer. As a subassembly, no Federal Communications Commission verification or certification of the device is required.

Seagate has tested this device in enclosures as described above to ensure that the total assembly (enclosure, disk drive, motherboard, power supply, etc.) does comply with the limits for a Class B computing device, pursuant to Subpart J, Part 15 of the FCC rules. Operation with noncertified assemblies is likely to result in interference to radio and television reception.

**Radio and television interference.** This equipment generates and uses radio frequency energy and if not installed and used in strict accordance with the manufacturer's instructions, may cause interference to radio and television reception.

This equipment is designed to provide reasonable protection against such interference in a residential installation. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause interference to radio or television, which can be determined by turning the equipment on and off, users are encouraged to try one or more of the following corrective measures:

- · Reorient the receiving antenna.
- Move the device to one side or the other of the radio or TV.
- Move the device farther away from the radio or TV.
- Plug the computer into a different outlet so that the receiver and computer are on different branch outlets.

If necessary, users should consult a dealer or an experienced radio/television technician for additional suggestions. Users may find helpful the following booklet prepared by the Federal Communications Commission: *How to Identify and Resolve Radio-Television Interference Problems*. This booklet is available from the Superintendent of Documents, U.S. Government Printing Office, Washington, DC 20402. Refer to publication number 004-000-00345-4.

#### 2.12 Environmental protection

Seagate designs its products to meet environmental protection requirements worldwide, including regulations restricting certain chemical substances.

#### 2.12.1 European Union Restriction of Hazardous Substance Law

#### 2.12.2 Restriction of Hazardous Substances in Electrical and Electronic Equipment

Seagate drives are designed to be compliant with the European Union RoHS "Recast" Directive 2011/65/EU (RoHS 2) as amended by Directive (EU) 2015/863. The RoHS2 restricts the use of certain hazardous substances such as Lead, Cadmium, Mercury, Hexavalent Chromium, Polybrominated Biphenyls (PBB) and Polybrominated Diphenyl Ether (PBDE), BisBis(2-Ethylhexyl) phthalate (DEHP), Benzyl butyl phthalate (BBP), Dibutyl phthalate (DBP), and Diisobutyl phthalate (DIBP) in electrical and electronic equipment (EEE).

#### 2.12.2.1 Substances of Very High Concern (SVHC)

The European Union REACH (Registration, Evaluation, Authorization and Restriction of Chemicals) Regulation (EC) 1907/2006 regulates chemicals shipped into and used in Europe. A number of parts and materials in Seagate products are procured from external suppliers. We rely on the representations of our suppliers regarding the presence of REACH substances in these articles and materials. Our supplier contracts require compliance with our chemical substance restrictions, and our suppliers document their compliance with our requirements by providing full-disclosure material content declarations that disclose inclusion of any REACH-regulated substance in such articles or materials. Product-specific REACH declarations are available upon request through your Seagate Sales Representative.

#### 2.12.3 China Requirements — China RoHS 2



China RoHS 2 refers to the Ministry of Industry and Information Technology Order No. 32, effective July 1, 2016, titled Management Methods for the Restriction of the Use of Hazardous Substances in Electrical and Electronic Products. To comply with China RoHS 2, Seagate determines this product's Environmental Protection Use Period (EPUP) to be 20 years in accordance with the *Marking for the Restricted Use of Hazardous Substances in Electronic and Electrical Products,* SJT 11364-2014.

#### **Table 5 China - Hazardous Substances**

部件名称	有害物质 Hazardous Substances						
Part Name	铅 (Pb)	汞 (Hg)	镉 (Cd)	六价铬 (Cr <sup>+6</sup> )	多溴联苯 (PBB)	多溴二苯醚 (PBDE)	
硬盘驱动器 HDD	Х	0	0	0	0	0	
印刷电路板组装 PCBA	Х	0	0	0	0	0	

本表格依据 SJ/T 11364 的规定编制。

This table is prepared in accordance with the provisions of SJ/T 11364-2014

- O: 表示该有害物质在该部件所有均质材料中的含量均在 GB/T 26572 规定的限量要求以下。
- O: Indicates that the hazardous substance contained in all of the homogeneous materials for this part is below the limit requirement of GB/T26572.
- X:表示该有害物质至少在该部件的某一均质材料中的含量超出 GB/T 26572 规定的限量要求。
- X: Indicates that the hazardous substance contained in at least one of the homogeneous materials used for this part is above the limit requirement of GB/T26572.

#### 2.12.4 Taiwan Requirements — Taiwan RoHS

Taiwan RoHS refers to the Taiwan Bureau of Standards, Metrology and Inspection's (BSMI) requirements in standard CNS 15663, Guidance to reduction of the restricted chemical substances in electrical and electronic equipment. Seagate products must comply with the "Marking of presence" requirements in Section 5 of CNS 15663, effective January 1, 2018. This product is Taiwan RoHS compliant.

The following table meets the Section 5 "Marking of presence" requirements.

**Table 6 Taiwan - Restricted Substances** 

設備名稱: 硬盤設備,型號: 僅適用于內部使用 Equipment Name: Hard Disk Device, Type Designation: Internal Use Only						
單元	限用物質及其化學符號 Restricted Substance and its chemical symbol					
Unit	鉛 (Pb)	汞 (Hg)	<b>鍋</b> (Cd)	六價鉻 (Cr <sup>+6</sup> )	多溴聯苯 (PBB)	多溴二苯醚 (PBDE)
硬盤驅動器 HDD	_	0	0	0	0	0
印刷電路板组装 PCBA	_	0	0	0	0	0

- 備考 1. "O" 係指該项限用物質之百分比含量未超出百分比含量基準值。
- Note 1. "O" indicates that the percentage content of the restricted substance does not exceed the percentage of reference value of presence.
- 備考 2. "—" 係指該项限用物質為排除項目。
- Note 2. "—" indicates that the restricted substance corresponds to the exemption.

#### 2.13 Corrosive environment

Seagate electronic drive components pass accelerated corrosion testing equivalent to 10 years exposure to light industrial environments containing sulfurous gases, chlorine and nitric oxide, classes G and H per ASTM B845. However, this accelerated testing cannot duplicate every potential application environment.

Users should use caution exposing any electronic components to uncontrolled chemical pollutants and corrosive chemicals as electronic drive component reliability can be affected by the installation environment. The silver, copper, nickel and gold films used in hard disk drives are especially sensitive to the presence of sulfide, chloride, and nitrate contaminants. Sulfur is found to be the most damaging. Materials used in cabinet fabrication, such as vulcanized rubber, that can outgas corrosive compounds should be minimized or eliminated. The useful life of any electronic equipment may be extended by replacing materials near circuitry with sulfide-free alternatives.

Seagate recommends that data centers be kept clean by monitoring and controlling the dust and gaseous contamination. Gaseous contamination should be within ANSI/ISA S71.04-2013 G2 classification levels (as measured on copper and silver coupons), and dust contamination to ISO 14644-1 Class 8 standards, and MTBF rated conditions as defined in the Annualized Failure Rate (AFR) and Mean Time Between Failure (MTBF) section.

## 2.14 Shipping, Repair and Returns

#### **Shipping**

When transporting or shipping a drive, use only a Seagate-approved container. Keep the original box. Seagate approved containers are easily identified by the Seagate Approved Package label. Shipping a drive in a non-approved container voids the drive warranty.

Seagate repair centers may refuse receipt of components improperly packaged or obviously damaged in transit. Contact the authorized Seagate distributor to purchase additional boxes. Seagate recommends shipping by an air-ride carrier experienced in handling computer equipment.

#### **Product repair and return information**

Seagate customer service centers are the only facilities authorized to service Seagate drives. Seagate does not sanction any third-party repair facilities. Any unauthorized repair or tampering with the factory seal voids the warranty.

# 3.0 Configuring and mounting the drive

This section contains the specifications and instructions for configuring and mounting the drive.

# 3.1 Handling and static-discharge precautions

After unpacking, and before installation, the drive may be exposed to potential handling and electrostatic discharge (ESD) hazards. Observe the following standard handling and static-discharge precautions:

Caution

- Before handling the drive, put on a grounded wrist strap, or ground oneself frequently by touching the metal chassis of a computer that is plugged into a grounded outlet. Wear a grounded wrist strap throughout the entire installation procedure.
- Handle the drive by its edges or frame only.
- The drive is extremely fragile—handle it with care. Do not press down on the drive top cover.
- Always rest the drive on a padded, antistatic surface until mounting it in the computer.
- Do not touch the connector pins or the printed circuit board.
- Do not remove the factory-installed labels from the drive or cover them with additional labels. Removal voids the warranty. Some factory-installed labels contain information needed to service the drive. Other labels are used to seal out dirt and contamination.

# 3.2 Configuring the drive

Each drive on the Serial ATA interface connects point-to-point with the Serial ATA host adapter. There is no master/slave relationship because each drive is considered a master in a point-to-point relationship. If two drives are attached on one Serial ATA host adapter, the host operating system views the two devices as if they were both "masters" on two separate ports. Both drives behave as if they are Device 0 (master) devices.

#### 3.3 Serial ATA cables and connectors

The Serial ATA interface cable consists of four conductors in two differential pairs, plus three ground connections. The cable size may be 30 to 26 AWG with a maximum length of one meter (39.37 in). See Table 7 for connector pin definitions. Either end of the SATA signal cable can be attached to the drive or host.

For direct backplane connection, the drive connectors are inserted directly into the host receptacle. The drive and the host receptacle incorporate features that enable the direct connection to be hot pluggable and blind mateable.

For installations which require cables, users can connect the drive as illustrated in Figure 3.

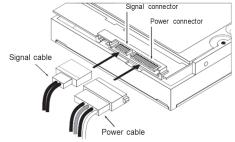


Figure 3. Attaching SATA cabling

Each cable is keyed to ensure correct orientation. SkyHawk AI drives support latching SATA connectors.

# 3.4 Drive mounting

Users can mount the drive in any orientation using four screws in the side-mounting holes or four screws in the bottom-mounting holes. See **Figure 4** for drive mounting dimensions. Follow these important mounting precautions when mounting the drive:

- Allow a minimum clearance of 0.030 in (0.76mm) around the entire perimeter of the drive for cooling.
- Use only 6-32 UNC mounting screws.
- The screws should be inserted no more than 0.140 in (3.56mm) into the bottom or side mounting holes.
- Do not overtighten the mounting screws (maximum torque: 6 in-lb).

#### 3.4.1 Mechanical specifications

Note

Refer to Figure 4 for detailed mounting configuration dimensions. See Section 3.4, "Drive mounting."

Weight:	10TB & 8TB models	1.43 lb	650 g
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These dimensions conform to the Small Form Factor Standard documented in SFF-8301 and SFF-8323, found at <a href="https://www.sffcommittee.org">www.sffcommittee.org</a>

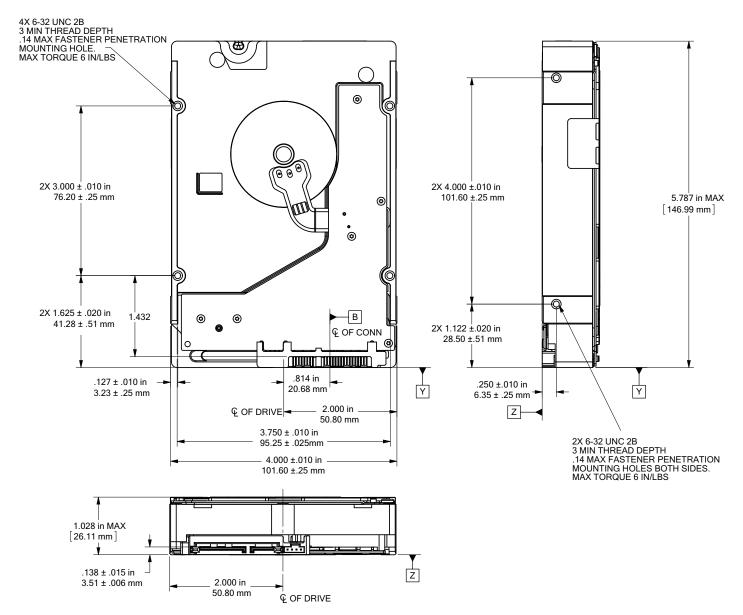


Figure 4. Mounting configuration dimensions

**Note** The image is for mechanical dimension reference only and may not represent the actual drive.

# 4.0 Serial ATA (SATA) interface

These drives use the industry-standard Serial ATA interface that supports FIS data transfers. It supports ATA programmed input/output (PIO) modes 0–4; multiword DMA modes 0–2, and Ultra DMA modes 0–6.

For detailed information about the Serial ATA interface, refer to the "Serial ATA: High Speed Serialized AT Attachment" specification.

# 4.1 Hot-Plug compatibility

SkyHawk AI drives incorporate connectors which enable users to hot plug these drives in accordance with the Serial ATA Revision 3.2 specification. This specification can be downloaded from <a href="https://www.serialata.org">www.serialata.org</a>.

#### **Caution:**

The drive motor must come to a complete stop (**Ready to spindle stop time indicated in Section 2.4**) prior to changing the plane of operation. This time is required to insure data integrity.

# 4.2 Serial ATA device plug connector pin definitions

Table 7 summarizes the signals on the Serial ATA interface and power connectors.

Table 7 Serial ATA connector pin definitions

Segment	Pin	Function	Definition		
	S1	Ground	2nd mate		
	S2	A+	Differential signal pair A from Phy		
	S3	A-	- Differential signal pair A from Friy		
Signal	S4	Ground	2nd mate		
	S5	B-	Differential signal pair B from Phy		
	S6	B+	- Differential signal pail bifform Fifty		
	S7	Ground	2nd mate		
Key and space	ing sep	arate signal and power segm	ents		
	P1	V <sub>33</sub>	3.3V power		
	P2	V <sub>33</sub>	3.3V power		
	P3	V <sub>33</sub>	3.3V power, pre-charge, 2nd mate		
	P4	Ground	1st mate		
	P5	Ground	2nd mate		
	P6	Ground	2nd mate		
	P7	V <sub>5</sub>	5V power, pre-charge, 2nd mate		
Power	P8	V <sub>5</sub>	5V power		
	P9	V <sub>5</sub>	5V power		
	P10	Ground	2nd mate		
	P11	Ground or LED signal	If grounded, drive does not use deferred spin		
	P12	Ground	1st mate.		
	P13	V <sub>12</sub>	12V power, pre-charge, 2nd mate		
	P14	V <sub>12</sub>	12V power		
	P15	V <sub>12</sub>	12V power		

#### Notes:

- 1. All pins are in a single row, with a 1.27mm (0.050") pitch.
- 2. The comments on the mating sequence apply to the case of backplane blindmate connector only. In this case, the mating sequences are:
  - the ground pins P4 and P12.
  - the pre-charge power pins and the other ground pins.
  - the signal pins and the rest of the power pins.
- 3. There are three power pins for each voltage. One pin from each voltage is used for pre-charge when installed in a blind-mate backplane configuration.
- 4. All used voltage pins (V<sub>x</sub>) must be terminated.

# 4.3 Supported ATA commands

The following table lists Serial ATA standard commands that the drive supports. For a detailed description of the ATA commands, refer to the Serial ATA: High Speed Serialized AT Attachment specification. See "S.M.A.R.T. commands" on page 33.for details and subcommands used in the S.M.A.R.T. implementation.

Table 8 Supported ATA commands

Accessible Max Address Configuration  Get Native Max Address Ext 78 <sub>H</sub> / 0000 <sub>H</sub> Set Accessible Max Address Ext 78 <sub>H</sub> / 0001 <sub>H</sub> Freeze Accessible Max Address Ext 78 <sub>H</sub> / 0002 <sub>H</sub> Check Power Mode E5 <sub>H</sub> Download Microcode 92 <sub>H</sub> Execute Device Diagnostics 90 <sub>H</sub> Flush Cache E7 <sub>H</sub> Flush Cache Extended EA <sub>H</sub> Identify Device EC <sub>H</sub> Idle Immediate E1 <sub>H</sub> NoP 00 <sub>H</sub>	
Set Accessible Max Address Ext 78 <sub>H</sub> / 0001 <sub>H</sub> Freeze Accessible Max Address Ext 78 <sub>H</sub> / 0002 <sub>H</sub> Check Power Mode E5 <sub>H</sub> Download Microcode 92 <sub>H</sub> Execute Device Diagnostics 90 <sub>H</sub> Flush Cache E7 <sub>H</sub> Flush Cache Extended EA <sub>H</sub> Identify Device EC <sub>H</sub> Idle E3 <sub>H</sub> Idle Immediate E1 <sub>H</sub>	
Freeze Accessible Max Address Ext 78 <sub>H</sub> / 0002 <sub>H</sub> Check Power Mode E5 <sub>H</sub> Download Microcode 92 <sub>H</sub> Execute Device Diagnostics 90 <sub>H</sub> Flush Cache E7 <sub>H</sub> Flush Cache Extended EA <sub>H</sub> Identify Device EC <sub>H</sub> Idle E3 <sub>H</sub> Idle Immediate E1 <sub>H</sub>	
Check Power Mode E5 <sub>H</sub> Download Microcode 92 <sub>H</sub> Execute Device Diagnostics 90 <sub>H</sub> Flush Cache E7 <sub>H</sub> Flush Cache Extended EA <sub>H</sub> Identify Device EC <sub>H</sub> Idle E3 <sub>H</sub> Idle Immediate E1 <sub>H</sub>	
Download Microcode 92 <sub>H</sub> Execute Device Diagnostics 90 <sub>H</sub> Flush Cache E7 <sub>H</sub> Flush Cache Extended EA <sub>H</sub> Identify Device EC <sub>H</sub> Idle E3 <sub>H</sub> Idle Immediate E1 <sub>H</sub>	
Execute Device Diagnostics 90 <sub>H</sub> Flush Cache E7 <sub>H</sub> Flush Cache Extended EA <sub>H</sub> Identify Device EC <sub>H</sub> Idle E3 <sub>H</sub> Idle Immediate E1 <sub>H</sub>	
Flush Cache E7 <sub>H</sub> Flush Cache Extended EA <sub>H</sub> Identify Device EC <sub>H</sub> Idle E3 <sub>H</sub> Idle Immediate E1 <sub>H</sub>	
Flush Cache Extended EA <sub>H</sub> Identify Device EC <sub>H</sub> Idle E3 <sub>H</sub> Idle Immediate E1 <sub>H</sub>	
Identify Device EC <sub>H</sub> Idle E3 <sub>H</sub> Idle Immediate E1 <sub>H</sub>	
Idle E3 <sub>H</sub> Idle Immediate E1 <sub>H</sub>	
Idle Immediate E1 <sub>H</sub>	
NoD	
NoP 00 <sub>H</sub>	
Read Buffer E4 <sub>H</sub>	
Read Buffer DMA E9 <sub>H</sub>	
Read DMA C8 <sub>H</sub>	
Read DMA Extended 25 <sub>H</sub>	
Read FPDMA Queued 60 <sub>H</sub>	
Read Log DMA Ext 47 <sub>H</sub>	
Read Log Ext 2F <sub>H</sub>	
Read Multiple C4 <sub>H</sub>	
Read Multiple Extended 29 <sub>H</sub>	
Read Sectors 20 <sub>H</sub>	
Read Sectors Extended 24 <sub>H</sub>	
Read Sectors Without Retries 21 <sub>H</sub>	
Read Verify Sectors 40 <sub>H</sub>	
Read Verify Sectors Extended 42 <sub>H</sub>	
Read Verify Sectors Without Retries 41 <sub>H</sub>	
Receive FPDMA Queued 65 <sub>H</sub>	
Request Sense Data Ext 0B <sub>H</sub>	
Sanitize Device - Overwrite Ext B4 <sub>H</sub> / 0014 <sub>H</sub>	
Sanitize Device - Freeze Lock Ext B4 <sub>H</sub> / 0020 <sub>H</sub>	
Sanitize Device - Status Ext B4 <sub>H</sub> / 0000 <sub>H</sub>	
Security Disable Password F6 <sub>H</sub>	
Security Erase Prepare F3 <sub>H</sub>	
Security Erase Unit F4 <sub>H</sub>	
Security Freeze F5 <sub>H</sub>	
Security Set Password F1 <sub>H</sub>	

Command name	Command code (in hex)
Security Unlock	F2 <sub>H</sub>
Seek	70 <sub>H</sub>
Send FPDMA Queued	64 <sub>H</sub>
Set Date & Time Ext	77 <sub>H</sub>
Set Features	EF <sub>H</sub>
Set Multiple Mode	C6 <sub>H</sub>
Sleep	E6 <sub>H</sub>
S.M.A.R.T. Disable Operations	B0 <sub>H</sub> / D9 <sub>H</sub>
S.M.A.R.T. Enable/Disable Autosave	BO <sub>H</sub> / D2 <sub>H</sub>
S.M.A.R.T. Enable Operations	BO <sub>H</sub> / D8 <sub>H</sub>
S.M.A.R.T. Execute Offline	BO <sub>H</sub> / D4 <sub>H</sub>
S.M.A.R.T. Read Attribute Thresholds	BO <sub>H</sub> / D1 <sub>H</sub>
S.M.A.R.T. Read Data	BO <sub>H</sub> / DO <sub>H</sub>
S.M.A.R.T. Read Log Sector	BO <sub>H</sub> / D5 <sub>H</sub>
S.M.A.R.T. Return Status	BO <sub>H</sub> / DA <sub>H</sub>
S.M.A.R.T. Save Attribute Values	BO <sub>H</sub> / D3 <sub>H</sub>
S.M.A.R.T. Write Log Sector	B0 <sub>H</sub> / D6 <sub>H</sub>
Standby	E2 <sub>H</sub>
Standby Immediate	EO <sub>H</sub>
Trusted Send	5E <sub>H</sub> (SED drives only)
Trusted Send DMA	5F <sub>H</sub> (SED drives only)
Trusted Receive	5C <sub>H</sub> (SED drives only)
Trusted Receive DMA	5D <sub>H</sub> (SED drives only)
Write Buffer	E8 <sub>H</sub>
Write Buffer DMA	EB <sub>H</sub>
Write DMA	CA <sub>H</sub>
Write DMA Extended	35 <sub>H</sub>
Write DMA FUA Extended	3D <sub>H</sub>
Write FPDMA Queued	61 <sub>H</sub>
Write Log DMA Ext	57 <sub>H</sub>
Write Log Extended	3F <sub>H</sub>
Write Multiple	C5 <sub>H</sub>
Write Multiple Extended	39 <sub>H</sub>
Write Multiple FUA Extended	CE <sub>H</sub>
Write Sectors	30 <sub>H</sub>
Write Sectors Without Retries	31 <sub>H</sub>
Write Sectors Extended	34 <sub>H</sub>
Write Uncorrectable	45 <sub>H</sub>

# 4.3.1 Identify Device command

The Identify Device command (command code EC<sub>H</sub>) transfers information about the drive to the host following power up. The data is organized as a single 512-byte block of data, whose contents are shown in Table 8 on page 27. All reserved bits or words should be set to zero. Parameters listed with an "x" are drive-specific or vary with the state of the drive. See Section 2.0 on page 7 for default parameter settings.

The following commands contain drive-specific features that may not be included in the Serial ATA specification.

Word	Description	Value
0	Configuration information:  • Bit 15: 0 = ATA; 1 = ATAPI  • Bit 7: removable media  • Bit 6: removable controller  • Bit 0: reserved	0C5A <sub>H</sub>
1	Obsolete	16,383
2	ATA-reserved	0000 <sub>H</sub>
3	Obsolete	16
4	Retired	0000 <sub>H</sub>
5	Retired	0000 <sub>H</sub>
6	Obsolete	003F <sub>H</sub>
7–9	Retired	0000 <sub>H</sub>
10–19	Serial number: (20 ASCII characters, 0000 <sub>H</sub> = none)	ASCII
20-21	Retired	0000 <sub>H</sub>
22	Obsolete	0000 <sub>H</sub>
23–26	Firmware revision (8 ASCII character string, padded with blanks to end of string)	x.xx
27–46	Drive model number: (40 ASCII characters, padded with blanks to end of string)	
47	(Bits 7–0) Maximum sectors per interrupt on Read multiple and Write multiple (16)	8010 <sub>H</sub>
48	Trusted computing feature set supported bit 0 (SED only)	4001 <sub>H</sub>
49	Standard Standby timer, IORDY supported and may be disabled	2F00 <sub>H</sub>
50	Capabilities	4000 <sub>H</sub>
51-52	Obsolete	xxxx <sub>H</sub>
53-56	Words 54–58, 64–70 and 88 are valid	xxxx <sub>H</sub>
57–58	Obsolete	xxxx <sub>H</sub>
59	(Bit 15: 0) Block Erase Ext Not Supported (Bit 14: 1) Overwrite Ext Supported (Bit 13: X) Crypto Scramble Ext Supported (SED Only) (Bit 12: 1) Sanitize feature set supported (Bit 11: 1) Commands allowed during sanitize op as specified in ACS-3 (Bit 10: 1) Sanitize Antifreeze Lock Ext command supported	SC10 <sub>H</sub>
60–61	Total number of user-addressable LBA sectors available (see Section 2.2 for related information)  *Note: The maximum value allowed in this field is: 0FFFFFFF (268,435,455 sectors, 137GB). Drives with capacities over 137GB will have 0FFFFFFF in this field and the actual number of user-addressable LBAs specified in words 100-103. This is required for drives that support the 48-bit addressing feature.	0FFFFFFh*
62	Obsolete	0000 <sub>H</sub>
63	Multiword DMA active and modes supported (see note following this table)	xx07 <sub>H</sub>
64	Advanced PIO modes supported (modes 3 and 4 supported)	0003 <sub>H</sub>
65	Minimum multiword DMA transfer cycle time per word (120 ns)	0078 <sub>H</sub>
66	Recommended multiword DMA transfer cycle time per word (120 ns)	0078 <sub>H</sub>

Word	Description	Value
67	Minimum PIO cycle time without IORDY flow control (240 ns)	0078 <sub>H</sub>
68	Minimum PIO cycle time with IORDY flow control (120 ns)	0078 <sub>H</sub>
69	Additional supported	0008 <sub>H</sub>
70–74	ATA-reserved	0000 <sub>H</sub>
75	Queue depth	001F <sub>H</sub>
76	Serial ATA capabilities	8D0E <sub>H</sub>
77	(Bit 6:1) Send/Receive FPDMA Queued Commands Supported	xx4x <sub>H</sub>
78	Serial ATA features supported	xxxx <sub>H</sub>
79	Serial ATA features enabled	xxxx <sub>H</sub>
80	Major version number	07F0 <sub>H</sub>
81	Minor version number	0060 <sub>H</sub>
82	Command sets supported	306B <sub>H</sub>
83	Command sets supported	7561 <sub>H</sub>
84	Command sets support extension (see note following this table)	6173 <sub>H</sub>
85	Command sets enabled	3069 <sub>H</sub>
86	Command sets enabled	B441 <sub>H</sub>
87	Command sets enable extension	6173 <sub>H</sub>
88	Ultra DMA support and current mode (see note following this table)	xx7F <sub>H</sub>
89	Security erase time	xxxx <sub>H</sub>
90	Enhanced security erase time	xxxx <sub>H</sub>
92	Master password revision code	FFFE <sub>H</sub>
93	Hardware reset value	xxxx <sub>H</sub>
95–99	ATA-reserved	0000 <sub>H</sub>
100–103	Total number of user-addressable LBA sectors available (see Section 2.2 for related information). These words are required for drives that support the 48-bit addressing feature. Maximum value: 0000FFFFFFFFFFF.	ST10000VE0004 = 19,532,873,728 ST8000VE0004 = 15,628,053,168
104–105	ATA-reserved	0000 <sub>H</sub>
106	Physical/Logical sector size	6003 <sub>H</sub>
107	ATA-reserved	0000 <sub>H</sub>
108–111	The mandatory value of the world wide name (WWN) for the drive.  NOTE: This field is valid if word 84, bit 8 is set to 1 indicating 64-bit WWN support.	Each drive will have a unique value.
112–118	ATA-reserved	0000 <sub>H</sub>
119	Commands and feature sets supported	41DE <sub>H</sub>
120	Commands and feature sets supported or enabled	409C <sub>H</sub>
121-127	ATA-reserved	0000 <sub>H</sub>
128	Security status	0021 <sub>H</sub>
129–159	Seagate-reserved	xxxx <sub>H</sub>
160-205	ATA-reserved	0000 <sub>H</sub>
206	SCT Command Transport command set. If bit 0 is set to one, then the device supports SCT Command Transport. Bits 7:2 indicate individual SCT feature support.	xxBD <sub>H</sub>
207-254	ATA-reserved	0000 <sub>H</sub>
255	Integrity word	xxA5 <sub>H</sub>

**Note** See the bit descriptions below for words 63, 84, and 88 of the Identify Drive data.

De	scription	ı (if bit is set to 1)
	Bit	Word 63
	0	Multiword DMA mode 0 is supported.
	1	Multiword DMA mode 1 is supported.
	2	Multiword DMA mode 2 is supported.
	8	Multiword DMA mode 0 is currently active.
	9	Multiword DMA mode 1 is currently active.
	10	Multiword DMA mode 2 is currently active.
	Bit	Word 84
	0	SMART error logging is supported.
	1	SMART self-test is supported.
	2	Media serial number is supported.
	3	Media Card Pass Through Command feature set is supported.
	4	Streaming feature set is supported.
	5	GPL feature set is supported.
	6	WRITE DMA FUA EXT and WRITE MULTIPLE FUA EXT commands are supported.
	7	WRITE DMA QUEUED FUA EXT command is supported.
	8	64-bit World Wide Name is supported.
	9-10	Obsolete.
	11-12	Reserved for TLC.
	13	IDLE IMMEDIATE command with IUNLOAD feature is supported.
	14	Shall be set to 1.
	15	Shall be cleared to 0.
	Bit	Word 88
	0	Ultra DMA mode 0 is supported.
	1	Ultra DMA mode 1 is supported.
	2	Ultra DMA mode 2 is supported.
	3	Ultra DMA mode 3 is supported.
	4	Ultra DMA mode 4 is supported.
	5	Ultra DMA mode 5 is supported.
	6	Ultra DMA mode 6 is supported.
	8	Ultra DMA mode 0 is currently active.
	9	Ultra DMA mode 1 is currently active.
	10	Ultra DMA mode 2 is currently active.
	11	Ultra DMA mode 3 is currently active.
	12	Ultra DMA mode 4 is currently active.
	13	Ultra DMA mode 5 is currently active.
	14	Ultra DMA mode 6 is currently active.

#### 4.3.2 Set Features command

This command controls the implementation of various features that the drive supports. When the drive receives this command, it sets BSY, checks the contents of the Features register, clears BSY and generates an interrupt. If the value in the register does not represent a feature that the drive supports, the command is aborted. Power-on default has the read look-ahead and write caching features enabled. The acceptable values for the Features register are defined as follows

#### **Table 9** Set Features command values

02<sub>H</sub> Enable write cache (default).

O3<sub>H</sub> Set transfer mode (based on value in Sector Count register).

Sector Count register values:

00<sub>H</sub> Set PIO mode to default (PIO mode 2).

01<sub>H</sub> Set PIO mode to default and disable IORDY (PIO mode 2).

08<sub>H</sub> PIO mode 0

09<sub>H</sub> PIO mode 1

0A<sub>H</sub> PIO mode 2

0B<sub>H</sub> PIO mode 3

0C<sub>H</sub> PIO mode 4 (default)

20<sub>H</sub> Multiword DMA mode 0

21<sub>H</sub> Multiword DMA mode 1

22<sub>H</sub> Multiword DMA mode 2

40<sub>H</sub> Ultra DMA mode 0

41<sub>H</sub> Ultra DMA mode 1

42<sub>H</sub> Ultra DMA mode 2

43<sub>H</sub> Ultra DMA mode 3

44<sub>H</sub> Ultra DMA mode 4

45<sub>H</sub> Ultra DMA mode 5

46<sub>H</sub> Ultra DMA mode 6

10<sub>H</sub> Enable use of SATA features

55<sub>H</sub> Disable read look-ahead (read cache) feature.

82<sub>H</sub> Disable write cache

90<sub>H</sub> Disable use of SATA features

AA<sub>H</sub> Enable read look-ahead (read cache) feature (default).

F1<sub>H</sub> Report full capacity available

Note At power-on, or after a hardware or software reset, the default values of the features are as indicated above.

#### 4.3.3 S.M.A.R.T. commands

S.M.A.R.T. provides near-term failure prediction for disk drives. When S.M.A.R.T. is enabled, the drive monitors predetermined drive attributes that are susceptible to degradation over time. If self-monitoring determines that a failure is likely, S.M.A.R.T. makes a status report available to the host. Not all failures are predictable. S.M.A.R.T. predictability is limited to the attributes the drive can monitor. For more information on S.M.A.R.T. commands and implementation, see the *Draft ATA-5 Standard*.

SeaTools diagnostic software activates a built-in drive self-test (DST S.M.A.R.T. command for D4<sub>H</sub>) that eliminates unnecessary drive returns. The diagnostic software ships with all new drives and is also available at: <a href="http://www.seagate.com/support/downloads/seatools/">http://www.seagate.com/support/downloads/seatools/</a>.

This drive is shipped with S.M.A.R.T. features disabled. Users must have a recent BIOS or software package that supports S.M.A.R.T. to enable this feature. The table below shows the S.M.A.R.T. command codes that the drive uses.

Table 10 S.M.A.R.T. commands

Code in features register	S.M.A.R.T. command
D0 <sub>H</sub>	S.M.A.R.T. Read Data
D2 <sub>H</sub>	S.M.A.R.T. Enable/Disable Attribute Autosave
D3 <sub>H</sub>	S.M.A.R.T. Save Attribute Values
D4 <sub>H</sub>	S.M.A.R.T. Execute Off-line Immediate (runs DST)
D5 <sub>H</sub>	S.M.A.R.T. Read Log Sector
D6 <sub>H</sub>	S.M.A.R.T. Write Log Sector
D8 <sub>H</sub>	S.M.A.R.T. Enable Operations
D9 <sub>H</sub>	S.M.A.R.T. Disable Operations
DA <sub>H</sub>	S.M.A.R.T. Return Status

Note	If an appropriate code is not written to the Features Register, the
	command is aborted and $0x04$ (abort) is written to the Error register.



# **Seagate Technology LLC**

AMERICAS Seagate Technology LLC 10200 South De Anza Boulevard, Cupertino, California 95014, United States, 408-658-1000
ASIA/PACIFIC Seagate Singapore International Headquarters Pte. Ltd. 7000 Ang Mo Kio Avenue 5, Singapore 569877, 65-6485-3888
EUROPE, MIDDLE EAST AND AFRICA Seagate Technology SAS 16-18 rue du Dôme, 92100 Boulogne-Billancourt, France, 33 1-4186 1000

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